

System Size and Shape Dependence of Anisotropic Flow

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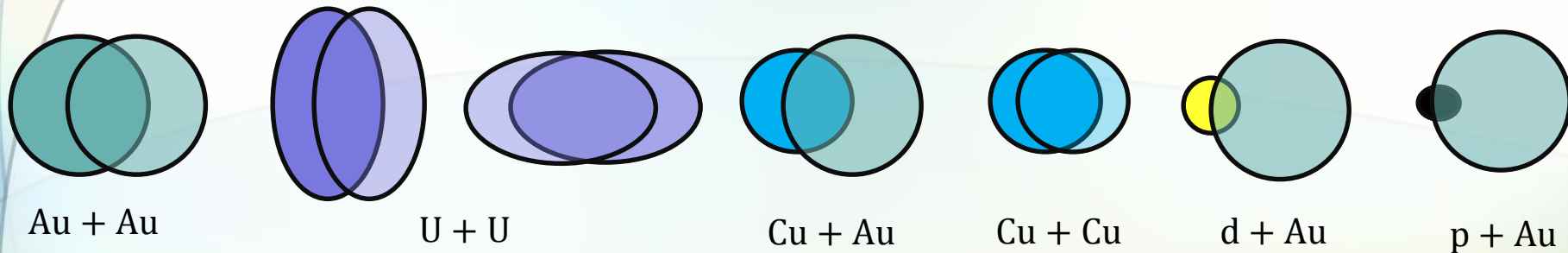
III. Conclusion

Motivation

- Is the observed anisotropy in ion-ion collision a final- or initial state effect?
- What are the essential differences between the medium created in small (p+A) and large (A+A) collision systems?
- Is there a limiting size to lose final-state effects ?

Motivation

- STAR collected data for different systems;



- v_n measurements for different systems are sensitive to system shape (ϵ_n), dimensionless size (RT) and transport coefficients $\left(\frac{\eta}{s}, \frac{\zeta}{s}, \dots\right)$.
- Scaling out the system shape and size $\xrightarrow{\text{yields}}$ $\left(\frac{\eta}{s}, \frac{\zeta}{s}, \dots\right)$ effect on v_n for each system.

Transport coefficients

➤ The v_n measurements are sensitive to ε_n , RT and $\left(\frac{\eta}{s}, \frac{\zeta}{s}, \dots\right)$.

➤ Acoustic ansatz

✓ Sound attenuation in the viscous matter reduces the magnitude of v_n .

➤ Anisotropic flow attenuation;

$$\frac{v_n}{\varepsilon_n} \propto e^{-\beta n^2}, \quad \beta \propto \frac{\eta}{s} \frac{1}{RT} + \dots$$

➤ From macroscopic entropy considerations $(RT)^3 \propto \frac{dN}{d\eta}$

$$\ln\left(\frac{v_n}{\varepsilon_n}\right) = a \frac{\eta}{s} \left(\frac{dN}{d\eta}\right)^{-\frac{1}{3}} + \ln(b)$$

$$\ln(v_n) = a \left(\frac{\eta}{s}\right) \left(\frac{dN}{d\eta}\right)^{-\frac{1}{3}} + \ln(\varepsilon_n) + \ln(b)$$

✓ Scaling out the system size $\left(\frac{dN}{d\eta}\right)$ and shape (ε_n) should give similar transport coefficient $\left(\frac{\eta}{s}\right)$ (i.e. similar v_n) for different systems (final state-effect).

PRC84 034908 (2011)
P.Staig and E.Shuryak

arXiv:1305.3341
Roy A. Lacey, A. Taranenko,
J. Jia, et al.

arXiv:1601.06001
Roy A. Lacey, Peifeng Liu,
Niseem Magdy, et al.

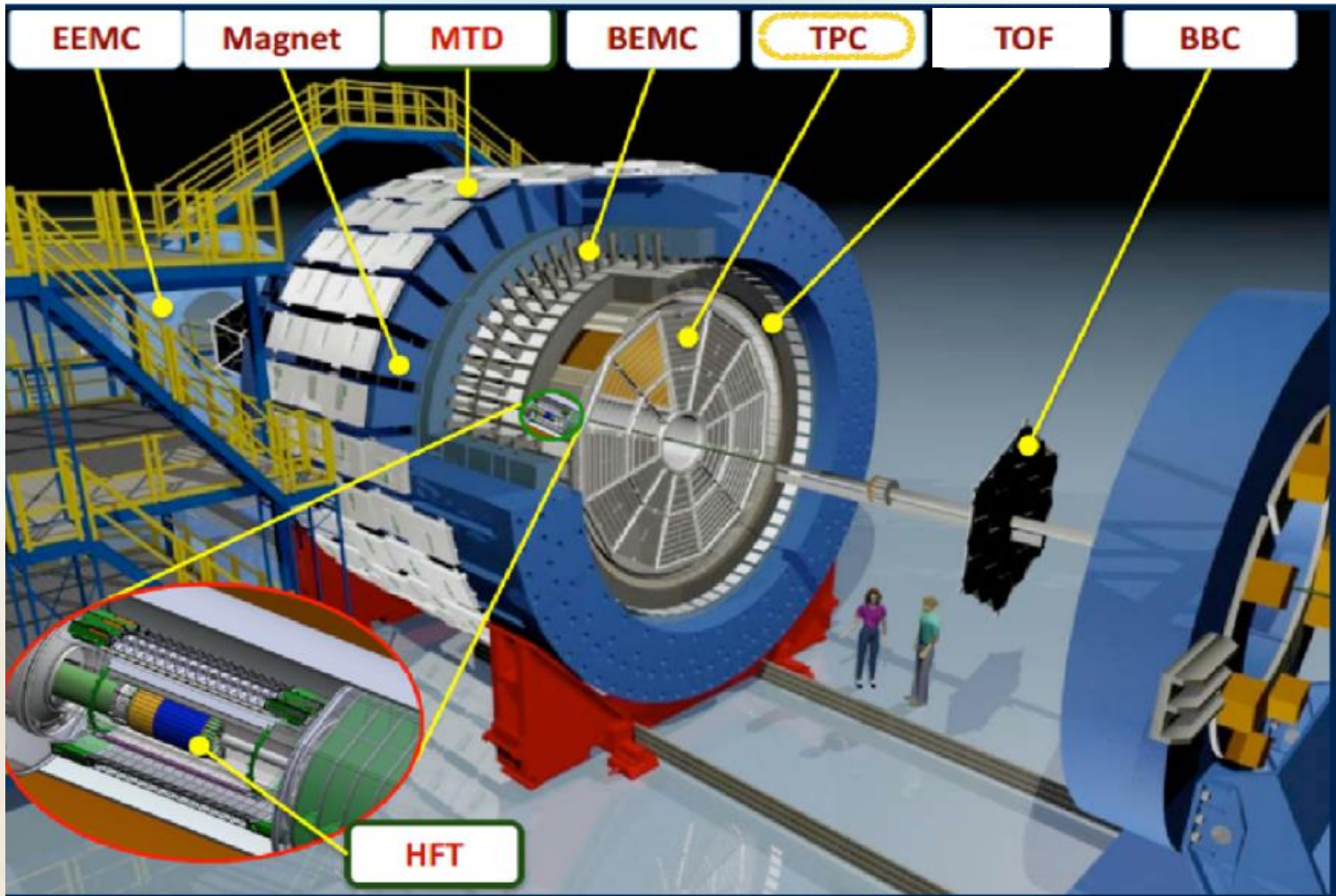
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STAR Detector at RHIC



➤ Uniform acceptance in $|\eta| < 1$

Correlation function technique

- All current techniques used to study v_n are related to the correlation function.

- Two particle correlation function $Cr(\Delta\varphi)$ used in this analysis,

$$Cr(\Delta\varphi) = \frac{dN/d\Delta\varphi(\text{same})}{dN/d\Delta\varphi(\text{mix})} \quad \text{and} \quad v_{nn} = \frac{\sum_{\Delta\varphi} Cr(\Delta\varphi) \cos(n \Delta\varphi)}{\sum_{\Delta\varphi} Cr(\Delta\varphi)}$$

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- Non-flow signals, as well as some residual detector effects (track merging/splitting) suppressed with $|\Delta\eta = \eta_1 - \eta_2| > 0.7$ cut.

$$v_{nn}(p_T^a, p_T^t) = v_n(p_T^a) v_n(p_T^t) \quad n > 1$$

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- ✓ Factorization ansatz for v_n ($n > 1$) verified.

$$v_{11}(p_T^a, p_T^t) = v_1^{\text{even}}(p_T^a) v_1^{\text{even}}(p_T^t) - C p_T^a p_T^t$$

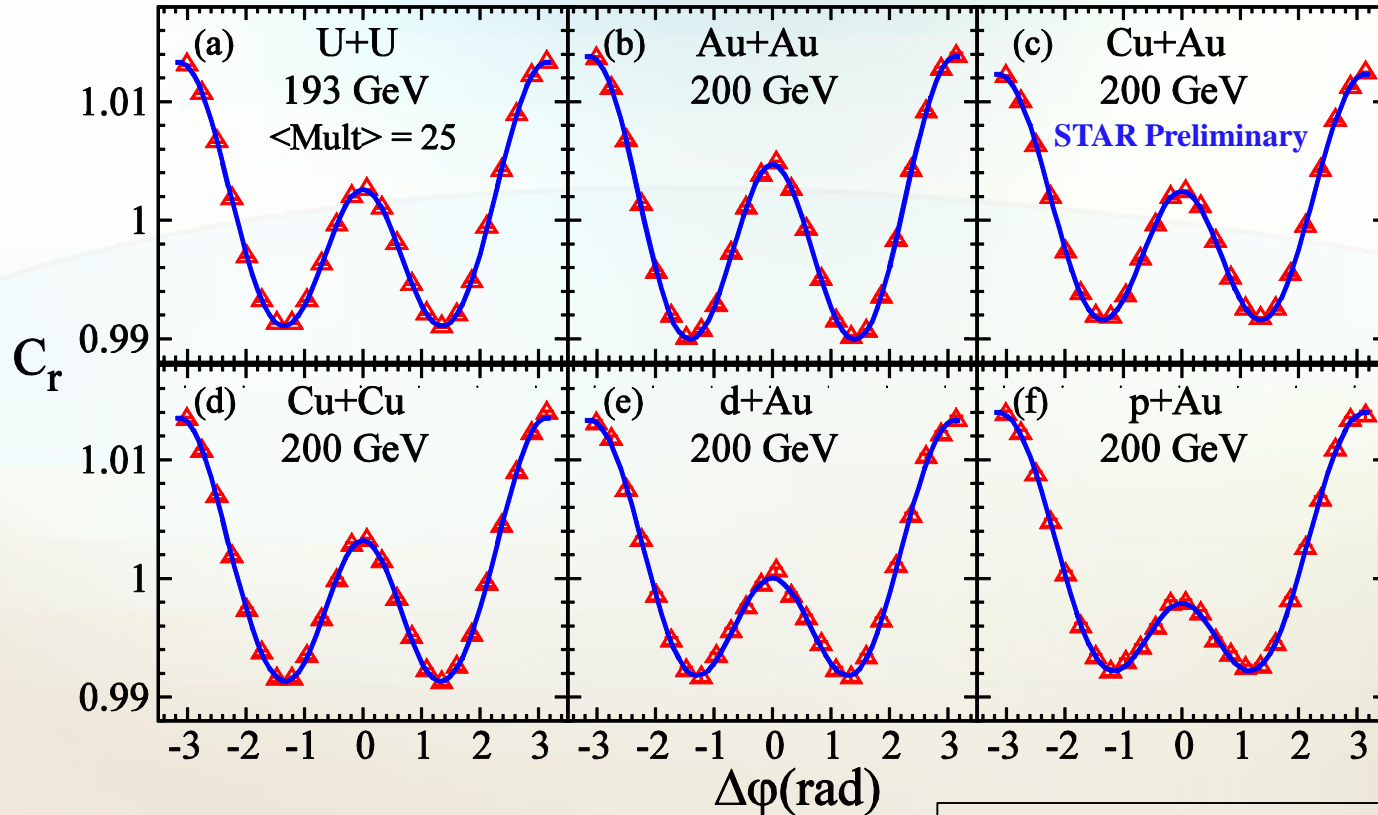
PRC 86, 014907 (2012)
ATLAS Collaboration

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- C is the momentum conservation parameter $C \propto \frac{1}{\langle \text{Mult} \rangle \langle p_T^2 \rangle}$

Correlation function

Different system correlation function



Using the correlating function we can extract v_{nn}

$$v_{nn} = \frac{\sum_{\Delta\phi} Cr(\Delta\phi) \cos(n \Delta\phi)}{\sum_{\Delta\phi} Cr(\Delta\phi)}$$

$v_n(p_T)$ for $n \neq 1$ as

$$v_n(p_T) = v_{nn}(p_{Tref}, p_T) / \sqrt{v_{nn}(p_{Tref})}$$

For $n = 1$?

For $n = 1$

Dipolar Flow

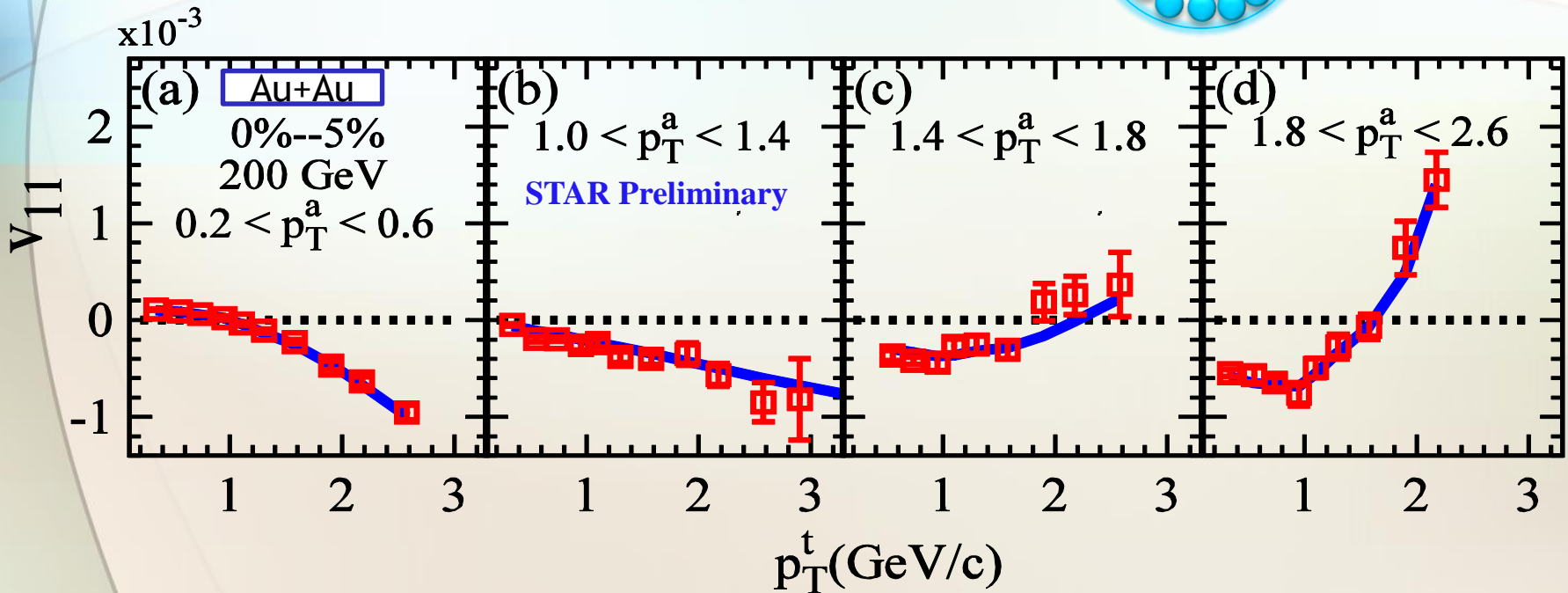
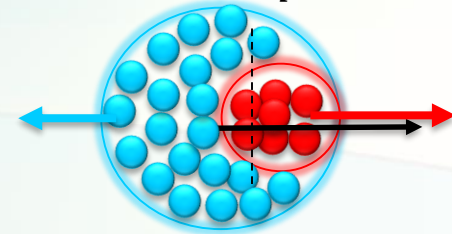
Simultaneous fit

$$v_{11}(p_T^a, p_T^t) = v_1^{even}(p_T^a) v_1^{even}(p_T^t) - C p_T^a p_T^t$$

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➤ v_{11} Eq[7] represents $N \times N$ matrix which we fit with $N + 1$ parameters

➤ Dipolar nature require that $\int_0^\infty \frac{dN}{dp_T} p_T v_1^{even} = 0$



➤ Good simultaneous fit obtained with fit function Eq[7].

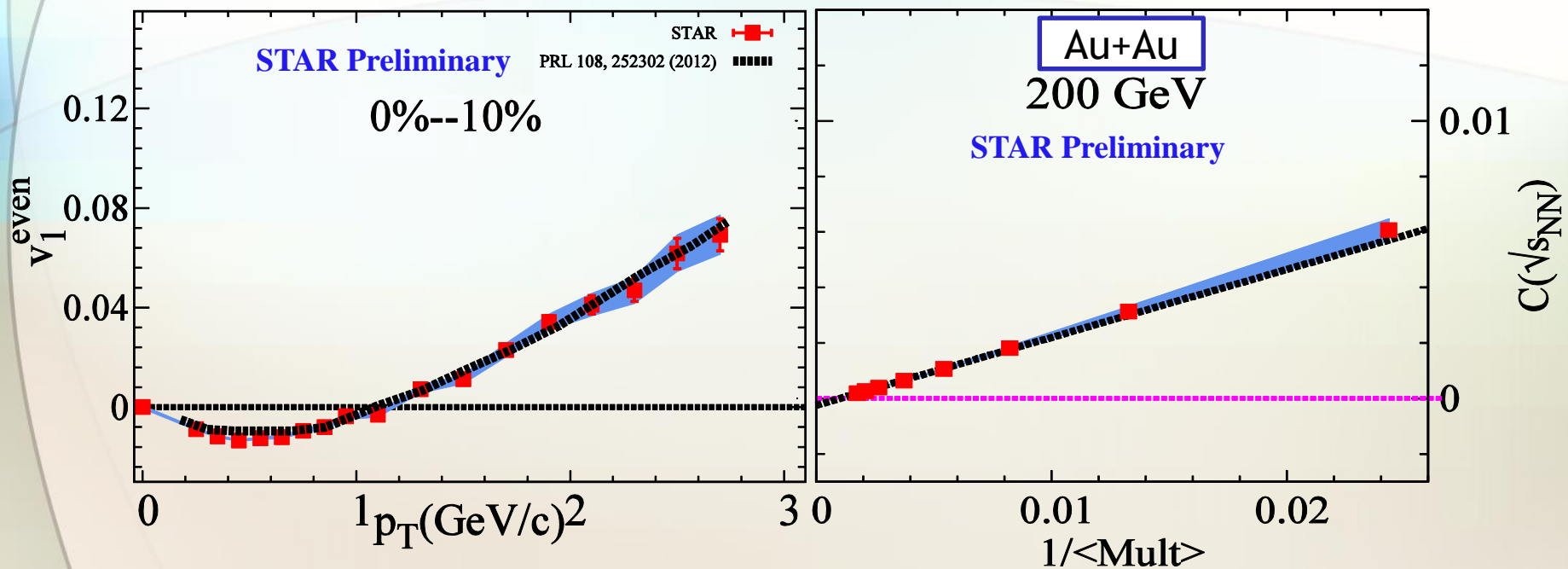
➤ v_{11} characteristic behavior gives a good constraint for $v_1^{even}(p_T)$ extraction.

Dipolar Flow

$$v_{11}(p_T^a, p_T^t) = v_1^{even}(p_T^a) v_1^{even}(p_T^t) - C p_T^a p_T^t$$

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- The extracted $v_1^{even}(p_T)$ and the momentum conservation parameter C at 200 GeV



- The characteristic behavior of $v_1^{even}(p_T)$ in good agreement with the hydrodynamics calculations
- The momentum conservation parameter C scales as $1/\langle \text{Mult} \rangle$

Results

$$|\eta| < 1 \text{ and } |\Delta\eta| > 0.7$$

System size effect

$$\ln(v_n) = a \left(\frac{\eta}{s}\right) \left(\frac{dN}{d\eta}\right)^{\frac{1}{3}} + \ln(\epsilon_n) + \ln(b)$$

System size and shape effect

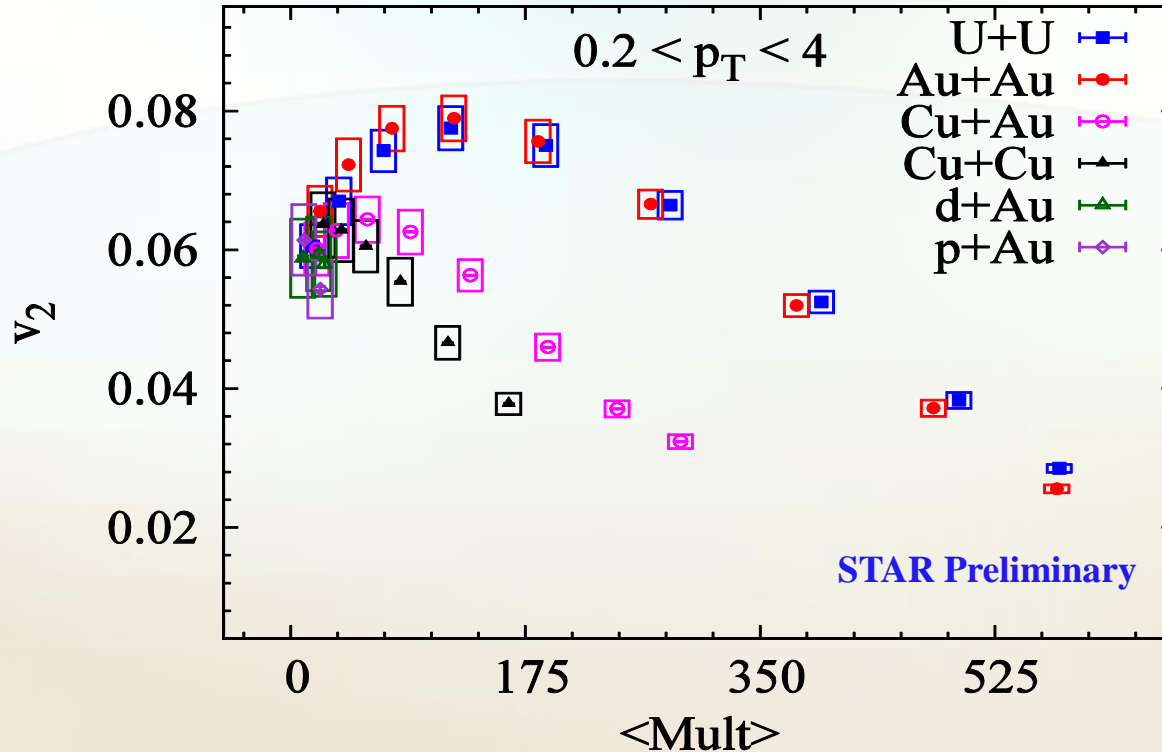
$$\ln(v_n) = a \left(\frac{\eta}{s}\right) \left(\frac{dN}{d\eta}\right)^{\frac{1}{3}} + \ln(\epsilon_n) + \ln(b)$$

$$v_n(Mult)$$

System size and shape

$$|\eta| < 1 \text{ and } |\Delta\eta| > 0.7$$

v_2 vs mean multiplicity for all systems



➤ $v_2(Mult)$ show similar trends for all systems.

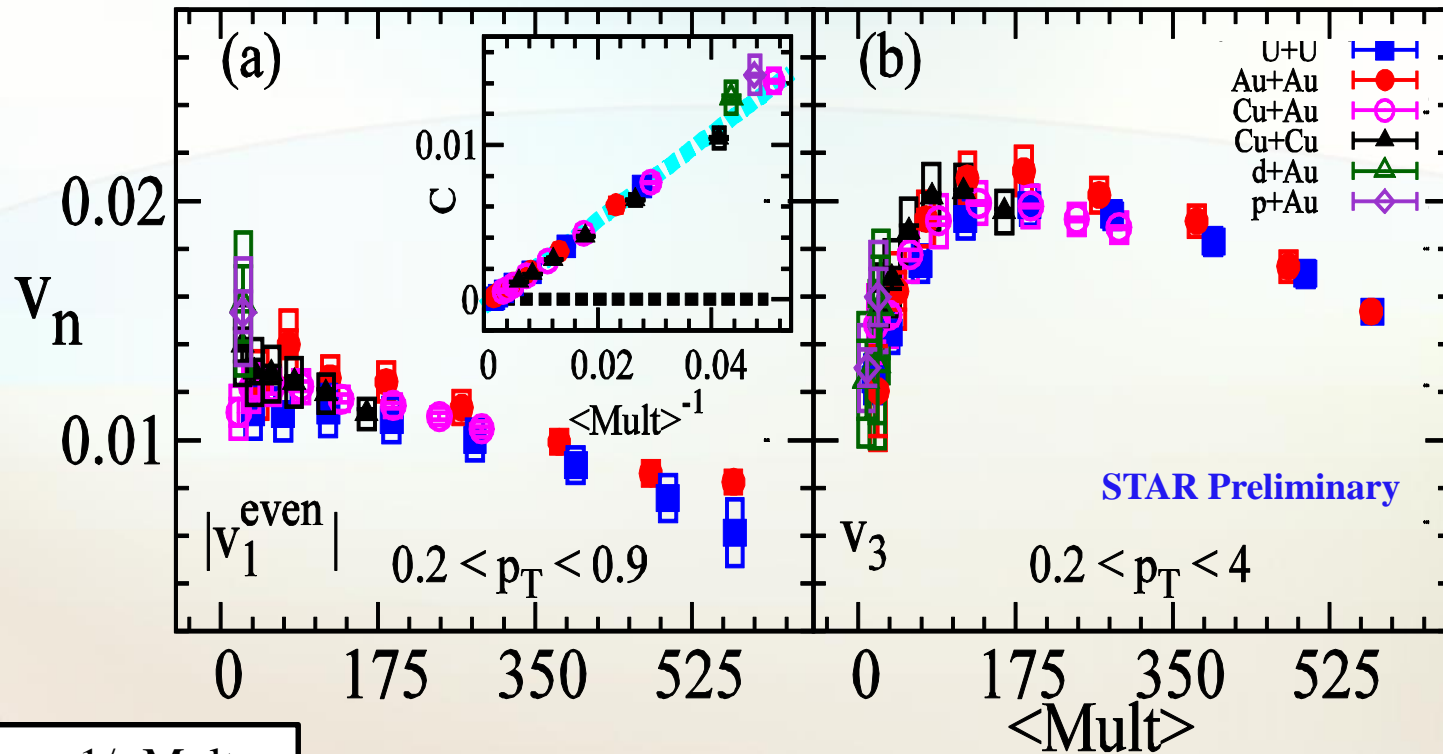
➤ v_2 is system dependent (shape).

$$v_n(\text{Mult})$$

System size

$$|\eta| < 1 \text{ and } |\Delta\eta| > 0.7$$

v_1^{even} and v_3 vs mean multiplicity for all systems



C scales as $1/\langle \text{Mult} \rangle$

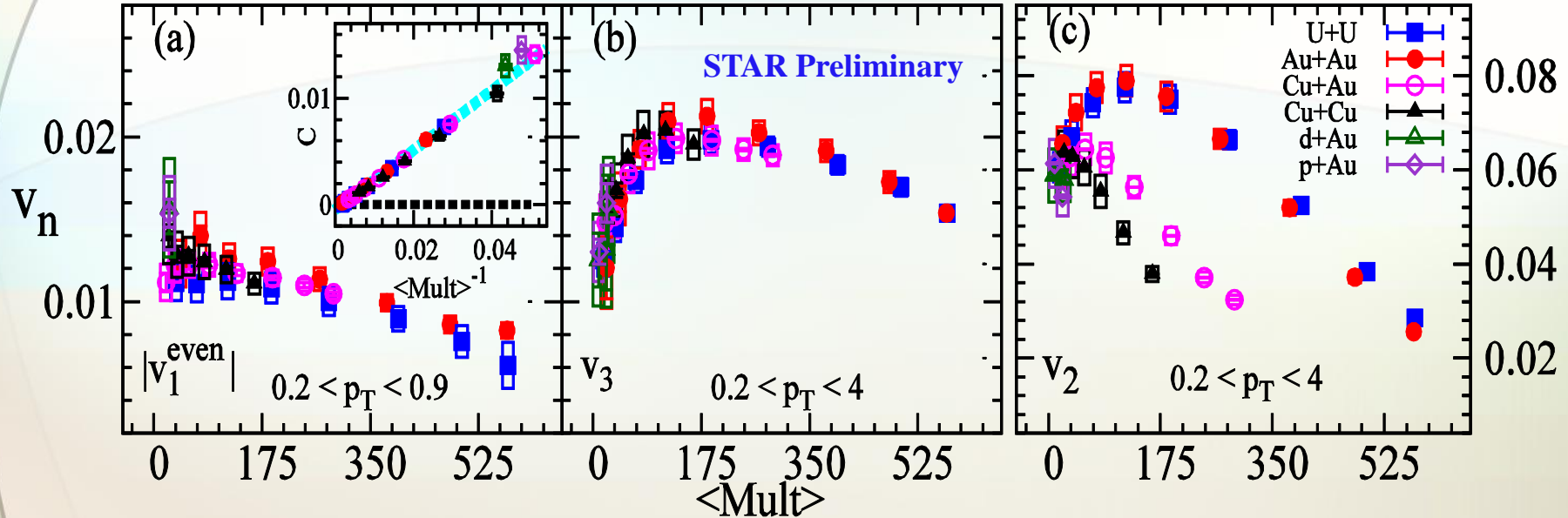
- v_1^{even} and v_3 show similar trends and magnitudes for all systems.
- v_1^{even} and v_3 are system independent (similar $\frac{\eta}{s}$).

$v_n(Mult)$

Summary

$$|\eta| < 1 \text{ and } |\Delta\eta| > 0.7$$

v_n mean multiplicity dependence for all systems

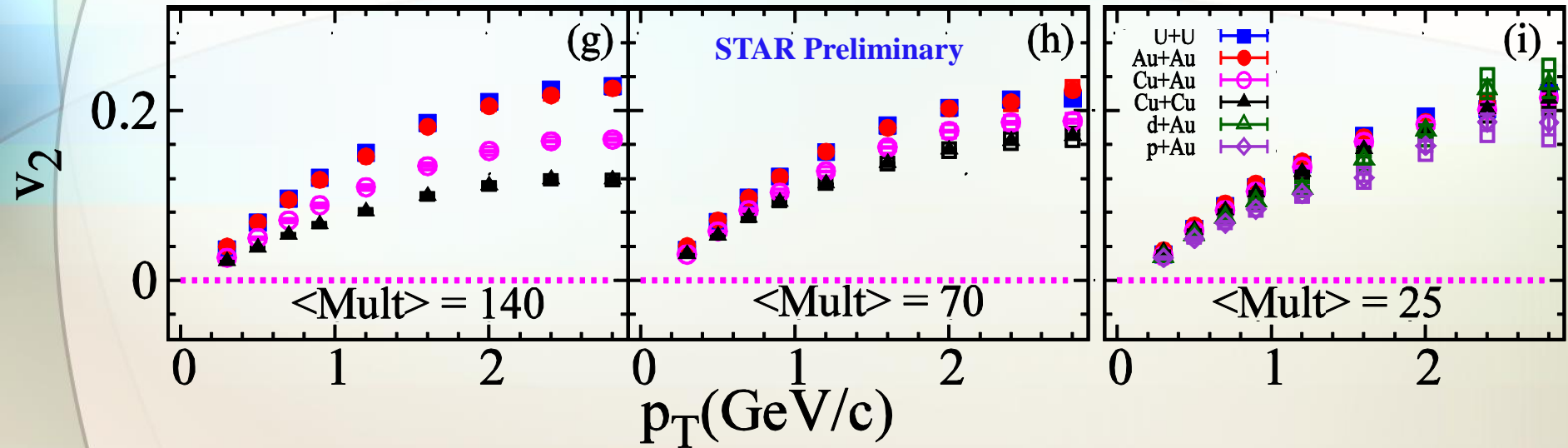


- For a given n , $v_n(p_T)$ show similar trends for all systems.
 - v_1^{even} and v_3 are system independent (similar $\frac{\eta}{s}$).
 - v_2 is system dependent.

$$v_n(p_T)$$

System size
 $|\eta| < 1$ and $|\Delta\eta| > 0.7$

v_2 vs p_T at fixed mean multiplicity for all systems



➤ v_2 show similar trends for all systems.

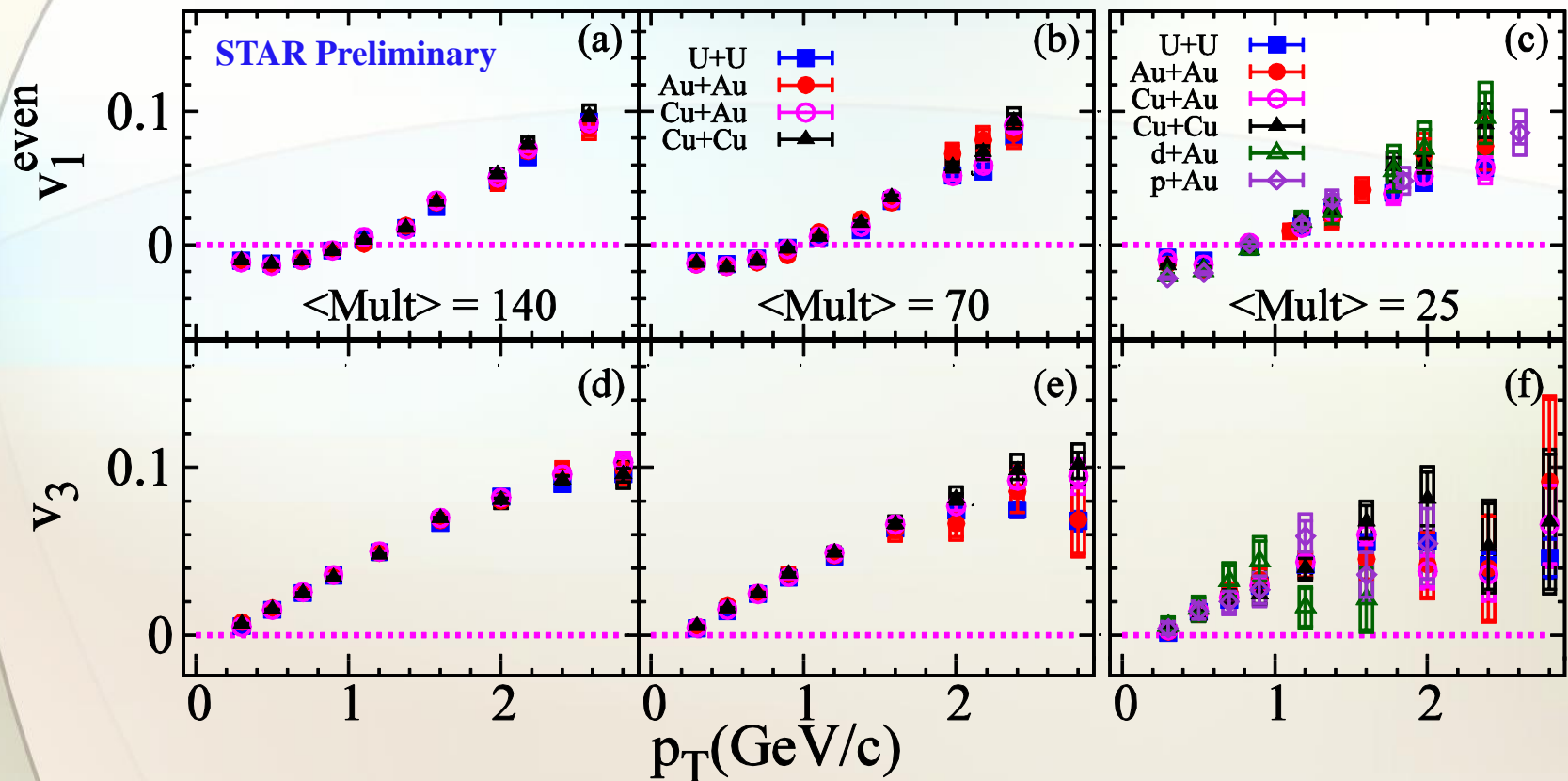
➤ v_2 is system dependent (shape).

$$v_n(p_T)$$

System size

$$|\eta| < 1 \text{ and } |\Delta\eta| > 0.7$$

v_1^{even} vs p_T at fixed mean multiplicity for all systems



➤ v_1^{even} and v_3 show similar trends and magnitudes for all systems.

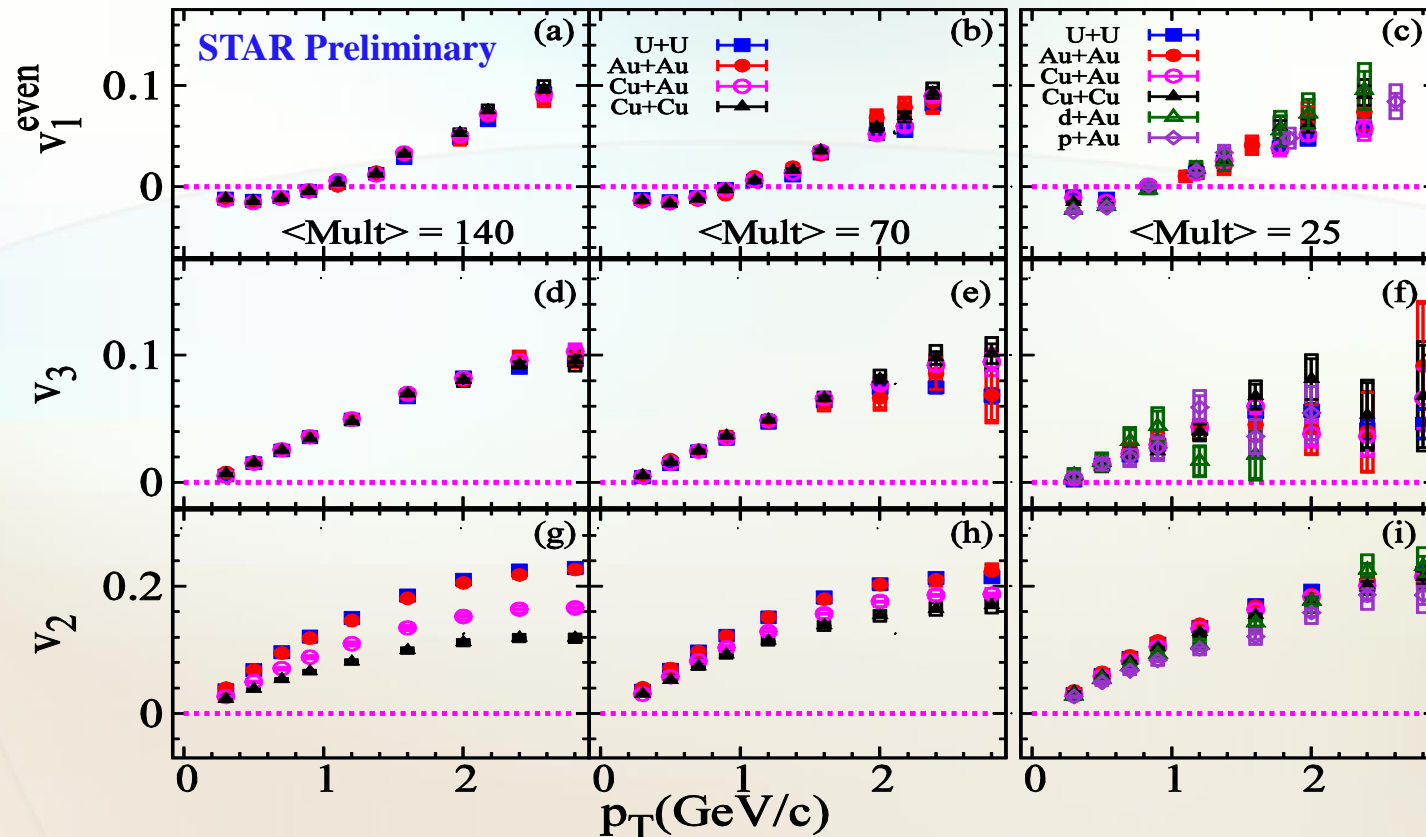
➤ v_1^{even} and v_3 is system independent (similar $\frac{\eta}{s}$).

$$v_n(p_T)$$

Summary

$$|\eta| < 1 \text{ and } |\Delta\eta| > 0.7$$

v_n vs p_T at fixed mean multiplicity for all systems



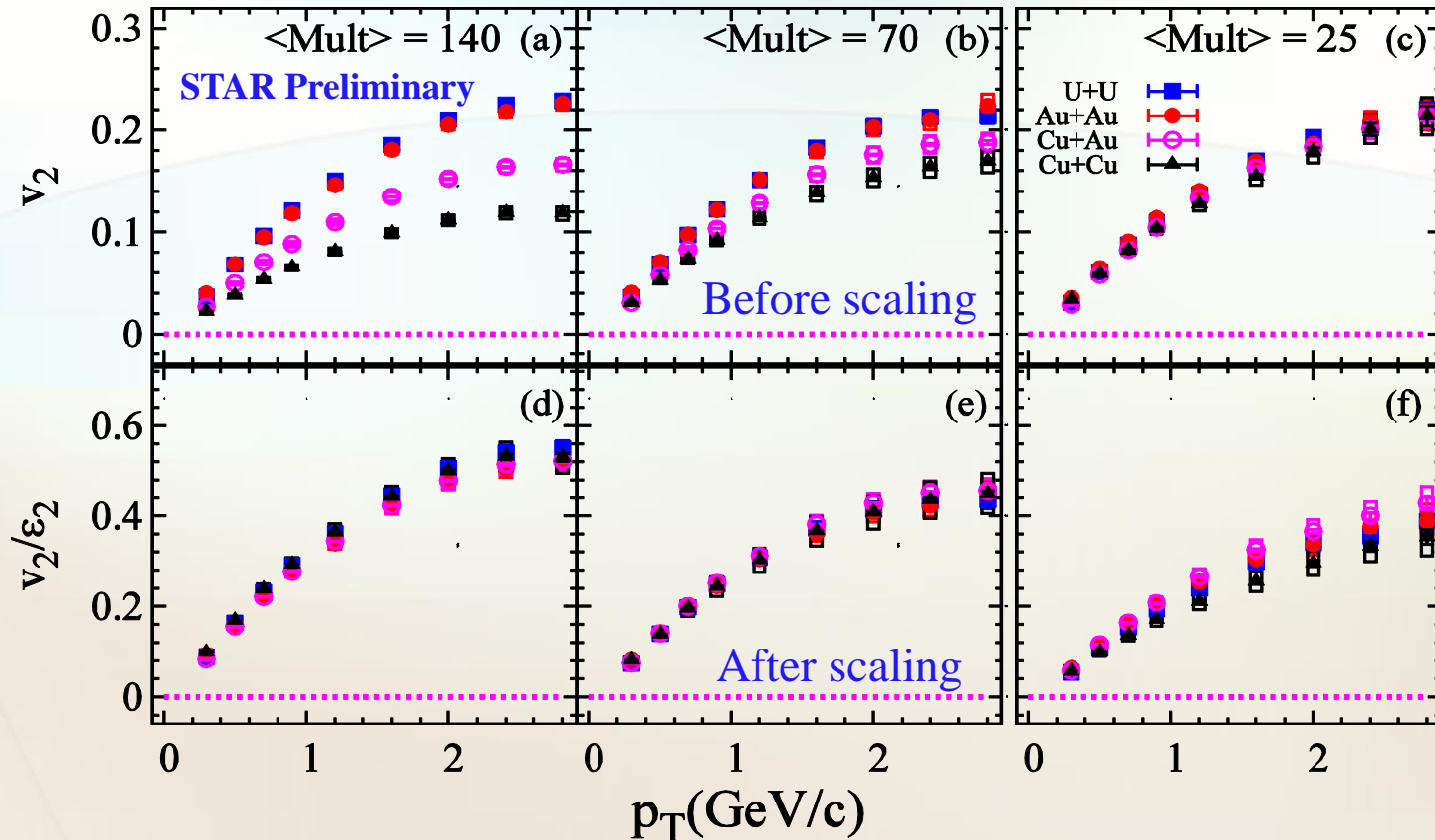
- For a given n , $v_n(p_T)$ show similar trends for all systems.
 - v_1^{even} and v_3 are system independent (similar $\frac{\eta}{s}$).
 - v_2 is system dependent (shape).

$$v_n(p_T)$$

System size and shape

$$|\eta| < 1 \text{ and } |\Delta\eta| > 0.7$$

$\frac{v_2}{\epsilon_2} p_T$ dependence at fixed mean multiplicity for all systems

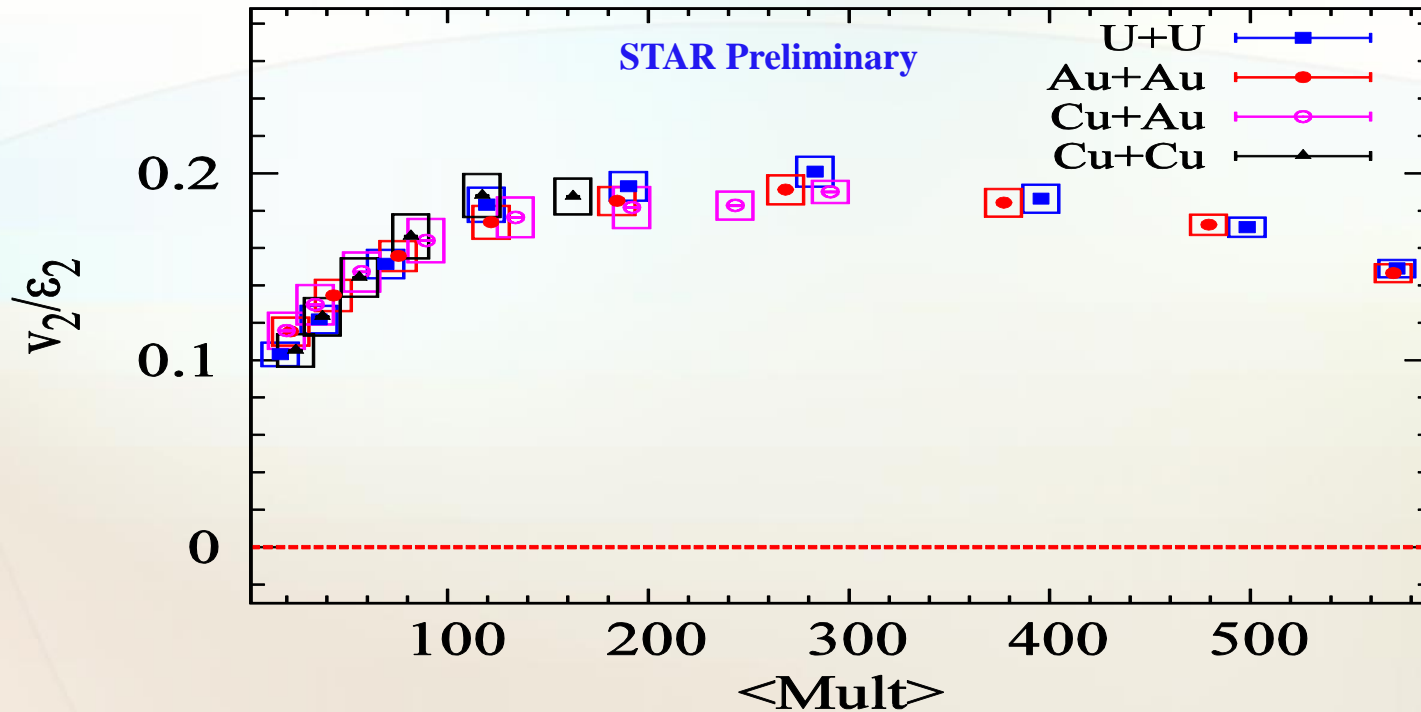


- $\frac{v_2}{\epsilon_2}(p_T)$ for all systems scales to a single curve.
- Similar $\frac{\eta}{s}$ for all systems.

$v_n(Mult)$

System size and shape
 $|\eta| < 1$ and $|\Delta\eta| > 0.7$

$\frac{v_2}{\epsilon_2}$ mean multiplicity dependence for all systems



- $\frac{v_2}{\epsilon_2}(Mult)$ for all systems scales to a single curve.
- Similar $\frac{\eta}{s}$ for all systems.

III. Conclusion

Comprehensive set of STAR measurements presented for $v_n(p_T, Mult)$ for several collision systems.

➤ For all systems;

- ✓ For $n = 1$, $v_1^{even}(p_T)$ shows the same characteristic behavior.
- ✓ For $n > 1$, v_n decreases with the harmonic order.

➤ Scaling the system size;

- ✓ The odd harmonics v_1^{even} and v_3 are shape independent
- ✓ $\frac{v_2}{\epsilon_2}$ for all systems scaled onto one curve
- ✓ Final state ansatz hold for presented systems

Scaling features suggest that all presented systems have similar transport coefficient $(\frac{\eta}{s})$ at $\sqrt{s_{NN}} \sim 200 \text{ GeV}$
(final-state effect)

III. Conclusion

Answers to initial questions?

- Is the observed anisotropy in ion-ion collision final- or initial state effect?
 - ✓ Final state ansatz hold for presented systems (p+Au, d+Au, Cu+Cu, Cu+Au, Au+Au and U+U).
- What are the essential differences between the medium created in small (p+A) and large (A+A) collision systems?
 - ✓ Size and shape are system dependent.
 - ✓ Scaled results suggest similar ($\frac{\eta}{s}$) for p+Au, d+Au, Cu+Cu, Cu+Au, Au+Au and U+U.
- Is there a limiting size to lose final state effects ?
 - ✓ All presented systems show evidence for strong final state effects.

THANK YOU